# IMPROVING SCHEDULING OF DATA TRANSMISSION IN TDMA SYSTEMS

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### ABSTRACT

In an era where communication has a most important role in modern societies, designing efficient algorithms for data transmission is of the outmost importance. TDMA is a technology used in many communication systems such as satellites and cell phones. In order to transmit data in such systems we need to cluster them in packages. To achieve a faster transmission we are allowed to preempt the transmission of any packet in order to resume at a later time. Such preemptions though come with a delay in order to setup for the next transmission. In this paper we propose an algorithm which yields improved transmission scheduling. This algorithm we call MGA. We have proven an approximation ratio for MGA and ran experiments to establish that it works even better in practice. In order to conclude that MGA will be a very helpful tool in constructing an improved schedule for packet routing using preemtion with a setup cost, we compare its results to two other efficient algorithms designed by researchers in the past.

## **KEYWORDS**

Communication networks, setup delay, preemption, packet routing

# **1. INTRODUCTION**

In the course of the last fifty years technological and scientific evolution has lead to an era of vast information and the need for fast and efficient communication. In the framework of enhancing communication network performance and dissemination of information researchers have introduced the Time Division Multiple Access (TDMA) technology. TDMA technology has been for decades a cornerstone of the global network infrastructure, as it plays an important role in many different communication systems.

To be more precise:

- Most 2G cellular systems are TDMA based. The GSM (Global System for Mobile Communications) currently accounts for approximately 80% of the subscribers worldwide. Many other 2G systems use TDMA technology among which are Personal Digital Cellular (PDC), the Digital Enhanced Cordless Telecommunications (DECT) standard for portable phones and PHS. Surprisingly enough 2G systems are not at all obsolete. They are still often used independently or in co-existence with the newest 3G and 4G systems.

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- TDMA technology is used in some 3G cellular systems such as the Universal Mobile Telecommunications System (UMTS).

- TDMA technology is also still used in satellite systems, in combat-net radio systems and in the Passive Optical Networks (PON).

TDMA based systems aim in transmitting data between multiple sender and receiver stations in packages simultaneously. While trying to reduce the time frame, preemption of a transmission is allowed in order to send the remaining parts of the messages at a later time with a newly scheduled package. Yet, in order to ready for the next package's transmission there is a setup cost which results in delaying the overall data transmission. Figure 1 depicts how a TDMA based technology transmission might work. This problem is referred to in bibliography as the MINSWT problem in case the number of frequencies does not suffice to serve all stations at once. In case the number of frequencies is at least as large as the number of senders as well as the number of receivers the problem is referred to as PBS. In this paper we handle the later. To this end we have designed a near optimal algorithm with an efficient approximation ratio. We have provided a proof for that approximation ratio and compared it to two other efficient algorithms handling the same problem. One which minimizes the number of packets and one which has the best approximation proven in bibliography so far.



Figure 1. TDMA transmission in a 3-source: $(t_1,t_2,t_3)$ , 3-receiver: $(r_1,r_2,r_3)$  system.

# 2. GRAPH REPRESENTATION AND NOTATIONS

For the purposes of our research we will represent an input instance by a bipartite graph G(V,U,E,w). V will denote the transmitters, U will stand for receivers, whereas the set of edges will comprise the information about data traffic through the TDMA system. The weight w(v,u),

assigned to each edge  $e=(v,u), v \in V, u \in U$  is the time required for the full transmission of each message.

Furthermore the following notation will be used:  $\Delta = \Delta(G) = \max\{\max_{v \in V} (\deg(v)), \max_{u \in U} (\deg(u))\},\$ 

that is,  $\Delta$  will denote degree of the bipartite graph which in practice equals to the maximum number of messages to be transferred from or to any of the stations.

 $W=W(G)=\max\{\max_{v\in V} \{\max_{u\in U} w(v,u)\}, \max_{u\in U} \{\sum_{v\in V} w(v,u)\}\}, \text{ that is } W \text{ will denote the maximum} \}$ 

total weight of all the edges adjacent to any of the nodes. This in turn equals to the maximum total workload of any station.

 $d \in Z_{+}^{*}$  will denote the setup delay, namely the time required so that the next transmission may begin.

The objective function to be minimized is  $F(G,d) = \sum_{i=1}^{N} t(M_i) + d \cdot N$ , where N is the number of distinct transmissions in order to transfer the entire data workload and  $t(M_i)$  is the time required for the completion of a specific transmission  $M_i$ .

Since transmission cannot be concluded before the maximum workload of any station is scheduled and the number of transmissions will be at least as many as the messages to be sent or received by any station, a lower bound to the optimal solution is LB=W+d· $\Delta$ . Yet, this lower bound is not always achievable as shown in [6].

### **3. PREVIOUS RESEARCH**

As shown in [4], PBS is  $4/3-\varepsilon$  inapproximable for any  $\varepsilon>0$ , unless P=NP. Even though the problem is NP-Hard there do exist special cases of input for which the optimal solution can be found in polynomial time ([1], [4], [5], [6]). The best approximation ratio proven so far is

 $2 - \frac{1}{d+1}$  by the authors of [1]. Experiments have been ran by many researchers to test the

output of various algorithms proposed in [2], [4], [5], [6], [10] and [12].

The performance of our newly presented algorithm will be compared to that of two algorithms found in bibliography:

- The algorithm presented in [8] which we will refer to as GWA (Gopal-Wong Algorithm). GWA calculates exactly  $\Delta$  matchings, corresponding to  $\Delta$  transmission packages. GWA will always achieve the minimum number of switchings and in order to produce a competitive transmission time for each package, the matchings are constructed so that edges of similar weight are grouped together. GWA has been tested in experiments in [6] and appears to perform well when the value of d increases significantly compared to duration of the messages. Unfortunately it has an unbounded approximation ratio as shown also in [6].

- A-PBS(d+1) as described in [1], preempts each edge to a multiple of d+1 and repeatedly computes matchings that correspond to transmission packets. Until now A-PBS(d+1) is the only algorithm that has a proven approximation ratio strictly less than 2. Yet, in most cases it produces schedules with makespan undesirably larger than the optimal.

Algorithm	Approximation ratio	Experimental results' conclusions
GWA	Unbounded	Works well only for large values of d and works undesirably bad for specific instances regardless the value of d.
A-PBS(d+1)	$2 - \frac{1}{d+1}$	Often produces results with more than 50% deviation from the optimal.
MGA	Δ+1	Produces efficient schedules on average as well in the worst case scenario regardless the input.

Table 1. Summary of the 3 algorithms comparison: GWA, A-PBS(d+1), MGA

Our newly developed algorithm, which we call MGA aims in mitigating these disadvantages of WGA and A-PBS(d+1). MGA tackles GWA's disadvantage, namely the fact that there are instances for which GWA produces a solution of unbounded approximation ratio and in addition it produces schedules that are on average a lot close to the optimal than those produced by A-PBS(d+1). Table 1 illustrates all of the above.

# 4. MGA: AN IMPROVED ROUTING ALGORITHM FOR DATA TRANSMISSION IN TDMA SYSTEMS

For the purposes of this paper we have designed an algorithm aiming in mitigating the disadvantage of GWA, namely an algorithm with a bounded approximation ratio. We will refer to this algorithm as MGA (MultiGraph Algorithm), as the main concept in order to achieve a bounded approximation ratio is to split each edge of undesirably large weight into smaller edges to be handled and scheduled independently.

The MultiGraph Algorithm (MGA)

*Step1:* Split each edge of weight more than  $\left\lfloor \frac{W}{\Delta} \right\rfloor$  in parts each having weight no more than |W|

 $\left\lfloor \frac{W}{\Delta} \right\rfloor$ . The splitting will be done in the following way: Split each edge  $e \in E$  with weight w(e)

into at most  $\left\lfloor \frac{W(e)\Delta}{W} \right\rfloor$  +1 edges the weight of each of which will be  $\left\lfloor \frac{W}{\Delta} \right\rfloor$  except perhaps for the

last one which will weigh  $w(e) - \left\lfloor \frac{w(e)\Delta}{W} \right\rfloor \cdot \left\lfloor \frac{W}{\Delta} \right\rfloor = w(e) \text{ MOD } \left\lfloor \frac{W}{\Delta} \right\rfloor$ . Thus G will become a

multigraph.

Step 2: Add nodes and edges to the multigraph in order to make it a regular multigraph. Each newly added edge e, will have w(e)=0.

*Step 3:* Compute a perfect matching for the regular multigraph and schedule the corresponding parts of the edges of this matching for transmission.

Step 4: Remove the edges corresponding to the previous transmission from the multigraph.

Step 5: repeat steps 3 and 4 until  $E=\emptyset$ .

*Theorem1:* MGA's approximation ratio is bounded by  $\Delta$ +1.

*Proof:* In the multigraph constructed by steps 1 and 2 the maximum edge weight is  $\left|\frac{W}{\Lambda}\right|$ .

Therefore the cost of each transmission will not exceed  $\left|\frac{W}{\Delta}\right|$ . The multigraph's degree is at

 $\operatorname{most} \Delta' \leq \left( \left\lfloor \frac{w_{\max} \cdot \Delta}{W} \right\rfloor + 1 \right) \cdot \Delta \text{ since there can be at most } \Delta \text{ edges to be split and each will be split in} \\ \left\lfloor \frac{w_{\max} \cdot \Delta}{W} \right\rfloor + 1 \text{ parts, where } w_{\max} \text{ is the maximum weight of any edge in the graph. Step 2 ensures}$ 

that each node has degree  $\Delta^{'}$  and that removing the edges of a perfect matching from G will reduce the graph's degree by exactly one after each iteration. Thus the number of terations will be  $\Delta'$ . Therefore the cost C of the entire process to transmit all data will be bounded by:

$$C \leq \left(\left\lfloor \frac{w_{\max} \cdot \Delta}{W} \right\rfloor + 1\right) \cdot \Delta \cdot \left\lfloor \frac{W}{\Delta} \right\rfloor + d \cdot \Delta' \leq \left(\left\lfloor \frac{w_{\max} \cdot \Delta}{W} \right\rfloor + 1\right) \cdot \Delta \cdot \left\lfloor \frac{W}{\Delta} \right\rfloor + d \cdot \left(\left\lfloor \frac{w_{\max} \cdot \Delta}{W} \right\rfloor + 1\right) \cdot \Delta$$

Taking into account that  $w_{max} \le W$ ,  $\lfloor a \rfloor \le a$ , for all  $a \in Q$  we conclude that

$$C \le \left(\frac{W \cdot \Delta}{W} + 1\right) \cdot \Delta \cdot \frac{W}{\Delta} + d \cdot \left(\frac{W \cdot \Delta}{W} + 1\right) \cdot \Delta = (\Delta + 1) \cdot W + d \cdot (\Delta + 1) \cdot \Delta = (\Delta + 1) \cdot (W + d \cdot \Delta)$$

Which implies that C $\leq$ ( $\Delta$ +1)·LB, thus bounding MGA's approximation ratio by  $\Delta$ +1

# 5. RUNNING TEST CASES TO EVALUATE THE PERFORMANCES OF THE THREE ALGORITHMS

One thousand test cases have been ran for a 50 source-50 destination system for values of setup cost varying from 0 to 100 and message durations varying from 0 to 100. We have to point out that since PBS is an NP-Hard problem, calculating an optimal schedule is inefficient therefore to estimate the approximation ratio we have used the lower bound to the optimal solution which is W+ $\Delta \cdot d$ .

Figure 2 establishes that MGA works better than GWA not only in the theoretical sense that theorem 1 implies but also in practice as well. We ran both algorithms using as input the "bad" instance presented in [6]. MGA will still yield an approximation ratio lower than 2 and will regardless the value of d perform better than GWA. We thereof have established that our newly presented algorithm will perform well, even for the worst transmission scenario.

Figure 3 presents the worst performance of MGA. It suggests that even though our proven approximation is  $\Delta$ -dependent, in practice MGA will not exceed an approximation ratio of 2 or even less. In fact MGA's (worst case/lower bound) will in no case exceed 1.55. Furthermore MGA's worst performance for any instance does not fluctuate much from its average performance, making it a stable and reliable tool for constructing an efficient schedule for the problem at hand.



Figure 2. Solution cost/lower bound comparison of GWA and MGA for a single "bad" instance.



Figure 4 compares MGA with A-PBS(d+1). A-PBS(d+1) will perform better only for very small values of d and even though it has a better approximation ratio, MGA produces a lot better results as d's value increases.



Figure 4: Average cost/lower bound comparison of A-PBS(d+1) and MGA

# 6. CONCLUSIONS AND FUTURE WORK

In this paper we have presented MGA, a  $\Delta$ +1- approximation algorithm for the problem of transmitting data packages through a TDMA based communication system. Furthermore, we ran experiments to establish how efficient MGA is in practice. Experiments suggest that it might be possible to prove a better approximation ratio than  $\Delta$ +1. That approximation ratio may even be less than two. We compared MGA with two algorithm found in bibliography. One which achieved the minimum number of preemtions and another which has the best approximation ratio proven so far, to establish that MGA works even better in practice. Yet, in order to prove MGA's approximation ratio we designed MGA so that it forcefully preempts transmission numerous times resulting in a schedule burdened by many delays. Future work might also suggest of a way to reduce the number of those preemptions leading to even better experimental results or even a proof for a lower approximation ratio.

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